

Chapter 1: Methodology of Microeconomics

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Theoretical Models

- Real world is extremely complex
 - Need to simplify or abstract: build economic models
 - Verification:
 - (a) Check assumptions
 - (b) Verify conclusions
 - Example: Do firms maximise profits?
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General Features

- Ceteris paribus: other things that affect are kept constant
 - Optimisation: Each agent pursue a goal
 - Firms minimise costs
 - Consumers maximise welfare
 - Governments maximise public welfare
 - Positive/Normative distinction:
 - positive: explain what happens
 - normative: what should be done
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Constrained Maximisation

- In many economic problems, we need to maximise objective function with a restriction

$$\begin{aligned} & \text{Max } f(x_1, \dots, x_n) \\ & \text{subject to } g(x_1, \dots, x_n) = 0 \end{aligned}$$

- Method: Maximise “Lagrangian” \mathcal{L} where

$$\mathcal{L} \equiv f(x_1, \dots, x_n) + \lambda g(x_1, \dots, x_n)$$

where λ is the Lagrange multiplier

- Results in a system of $n + 1$ equations with $n + 1$ unknowns

$$\begin{aligned} \frac{\partial \mathcal{L}}{\partial x_i} &= \frac{\partial f}{\partial x_i}(x_1, \dots, x_n) + \lambda \frac{\partial g}{\partial x_i}(x_1, \dots, x_n) = 0 \text{ for all } i \\ \frac{\partial \mathcal{L}}{\partial \lambda} &= \frac{\partial g}{\partial \lambda}(x_1, \dots, x_n) = 0 \end{aligned}$$

Example

$$\begin{aligned} \text{Max } f(x_1, x_2) &\equiv -x_1^2 + 2x_1 - x_2^2 + 4x_2 + 5 \\ \text{s.t. } x_1 + x_2 &= 1 \end{aligned}$$

- Maximising Lagrangian \mathcal{L}

$$\mathcal{L} \equiv -x_1^2 + 2x_1 - x_2^2 + 4x_2 + 5 + \lambda(1 - x_1 - x_2)$$

results in a system of 3 equations with 3 unknowns

$$-2x_1 + 2 - \lambda = 0$$

$$-2x_2 + 4 - \lambda = 0$$

$$1 - x_1 - x_2 = 0$$

- Solving $x_1 = 0$, $x_2 = 1$ and $\lambda = 2$ and $f(0, 1) = 8$
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Lagrange Multiplier

- Lagrange multiplier or shadow value λ satisfies

$$\lambda = \frac{\frac{\partial f}{\partial x_i}(x_1, \dots, x_n)}{-\frac{\partial g}{\partial x_i}(x_1, \dots, x_n)} \text{ for all } i$$

- Marginal change in objective function for a marginal “increase” in the constraint
- High λ : constraint is “very” binding, $\lambda = 0$: not binding at all
- In our example:

$$\lambda = \left| \frac{-2x_1 + 2}{1} \right|_{(0,1)} = \left| \frac{-2x_2 + 4}{1} \right|_{(0,1)} = 2$$

- Need to check second order conditions! Same for constrained minimisation
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